

# ACORN FAQ

## General Information

**IP Addresses:** **acorn.uconn.edu** (Recommended)\*

137.99.150.56 (Server 1 of 2)

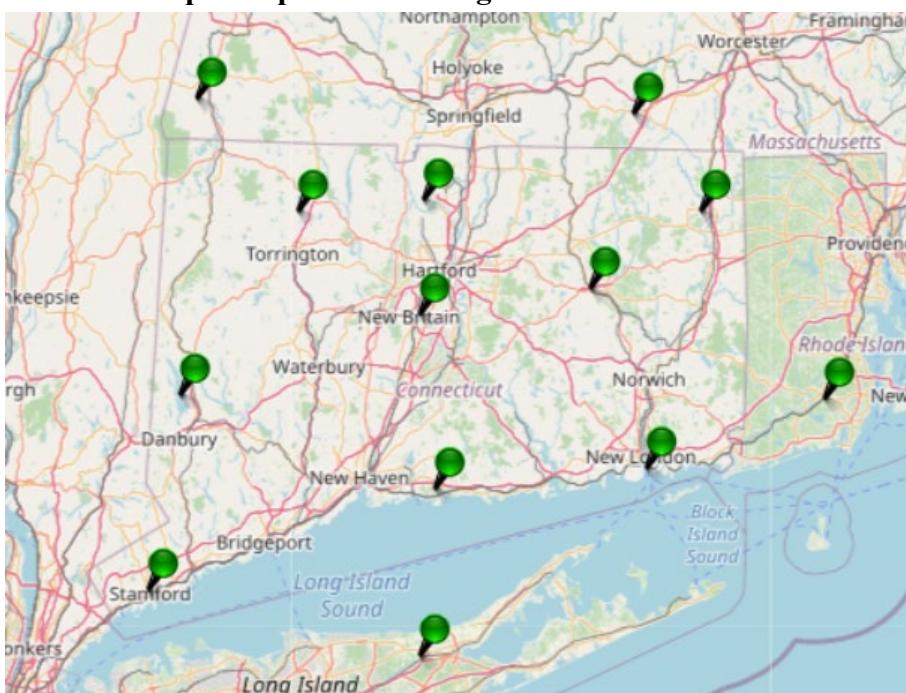
137.99.150.112 (Server 2 of 2)

Port #: 2101

\*Connecting to ACORN via the acorn.uconn.edu URL is highly recommended as the data collector will be automatically entered into ACORN's "round robin" system which distributes users to 1 of the 2 identical servers for load balancing purposes. Users may also opt to hardwire into a specific server by entering the numeric IP address.

### Sensor Map

Green pins represent existing ACORN CORS



Detailed station information can be found at <http://www.ngs.noaa.gov/CORS/> by entering the four-character station ID. FAQ document page 3 provides their coordinates.

| CORS ID | Location        |
|---------|-----------------|
| CTBK    | Brookfield, CT  |
| CTDA    | Darien, CT      |
| CTEG    | East Granby, CT |
| CTGR    | Groton, CT      |
| CTGU    | Guilford, CT    |
| CTMA    | Mansfield, CT   |
| CTNE    | Newington, CT   |
| CTPN    | Putnam, CT      |
| CTWI    | Winchester, CT  |
| MASB    | Sturbridge, MA  |
| MASH    | Sheffield, MA   |
| NYRH    | Riverhead, NY   |
| URIL    | Kingston, RI    |

### Mount Types (4)

**DGPS (differential)**

Single Station

Multi Station\*

VRS (virtual)

\* Not RTK with multiple bases. This directs ACORN to pick the closest base.

### Communication Protocols

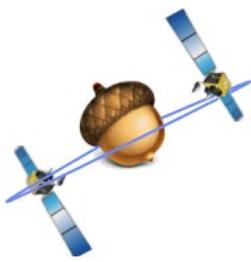
| Format | Description  | Bytes* |
|--------|--|--------|
| RTCM   | Radio Technical Commission for Maritime Services (version 3.1)       | 12,600 |
| CMRP   | Compact Measurement Record, also known as CMR+ and "CMR plus"        | 12,000 |
| CMRX   | Trimble proprietary, uses orbit information to further compress data | 5,500  |

\* Bytes based upon 1 minute of data, Single Station (no PBS, no VRS residuals), 11 satellites, Position and antenna every 8 epochs (or trickled over 8 epochs with CMR+/CMRx)

### OTHER TIPS

- ACORN uses Absolute Phase Center Variations (PCV) – do not mix Absolute and Relative!
- Security Profile: N/A – your security settings connect the receiver to wifi, not to ACORN
- Static observations are supported by ACORN – put it on the tripod and hit the button
- Contact the administrator if you need to change your password. Do not change it on your own in the web interface because the change will only take effect on one of the two servers.





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## Single Base Station Mount Points



| Mount Point ID | Base Station    | Communication Protocol | Antenna Type   |
|----------------|-----------------|------------------------|--|
| <b>BK3</b>     | Brookfield, CT  | RTCM v3.4              | Trimble Zephyr Geodetic Model 3 TRM115000.00 (no radome) |
| <b>BKP</b>     |                 | CMRP (no MSM)          |  |
| <b>BKX</b>     |                 | CMRX                   |  |
| <b>DA3</b>     | Darien, CT      | RTCM v3.4              | Trimble Zephyr Geodetic Model 2 TRM57971.00 (no radome)  |
| <b>DAP</b>     |                 | CMRP (no MSM)          |  |
| <b>DAX</b>     |                 | CMRX                   |  |
| <b>EG3</b>     | East Granby, CT | RTCM v3.4              | Trimble Zephyr Geodetic Model 2 TRM57971.00 (no radome)  |
| <b>EGP</b>     |                 | CMRP (no MSM)          |  |
| <b>EGX</b>     |                 | CMRX                   |  |
| <b>GR3</b>     | Groton, CT      | RTCM v3.4              | Trimble Zephyr Geodetic Model 2 TRM57971.00 (no radome)  |
| <b>GRP</b>     |                 | CMRP (no MSM)          |  |
| <b>GRX</b>     |                 | CMRX                   |  |
| <b>GU3</b>     | Guilford, CT    | RTCM v3.4              | Trimble Zephyr Geodetic Model 2 TRM57971.00 (no radome)  |
| <b>GUP</b>     |                 | CMRP (no MSM)          |  |
| <b>GUX</b>     |                 | CMRX                   |  |
| <b>MA3</b>     | Mansfield, CT   | RTCM v3.4              | Trimble Zephyr Geodetic Model 2 TRM57971.00 (no radome)  |
| <b>MAP</b>     |                 | CMRP (no MSM)          |  |
| <b>MAX</b>     |                 | CMRX                   |  |
| <b>NE3</b>     | Newington, CT   | RTCM v3.4              | Trimble Zephyr Geodetic Model 2 TRM57971.00 (no radome)  |
| <b>NEP</b>     |                 | CMRP (no MSM)          |  |
| <b>NEX</b>     |                 | CMRX                   |  |
| <b>PN3</b>     | Putnam, CT      | RTCM v3.4              | Trimble Zephyr Geodetic Model 3 TRM115000.00 (no radome) |
| <b>PNP</b>     |                 | CMRP (no MSM)          |  |
| <b>PNX</b>     |                 | CMRX                   |  |
| <b>NYRH3</b>   | Riverhead, NY   | RTCM v3.4              | Leica LEIAR10 (no radome)                                |
| <b>NYRHP</b>   |                 | CMRP (no MSM)          |  |
| <b>NYRHX</b>   |                 | CMRX                   |  |
| <b>MASB3</b>   | Sturbridge, MA  | RTCM v3.4              | Leica LEIAX1203 + GNSS (no radome)                       |
| <b>MASBP</b>   |                 | CMRP (no MSM)          |  |
| <b>MASBX</b>   |                 | CMRX                   |  |
| <b>MASH3</b>   | Sheffield, MA   | RTCM v3.4              | Leica LEIAX1203 + GNSS (no radome)                       |
| <b>MASHP</b>   |                 | CMRP (no MSM)          |  |
| <b>MASHX</b>   |                 | CMRX                   |  |
| <b>URIL3</b>   | Kingston, RI    | RTCM v3.4              | Trimble GNSS Choke Ring v2 w/SCIS Dome                   |
| <b>URILP</b>   |                 | CMRP (no MSM)          |  |
| <b>URILX</b>   |                 | CMRX                   |  |
| <b>WI3</b>     | Winchester, CT  | RTCM v3.4              | Trimble Zephyr Geodetic Model 2 TRM57971.00 (no radome)  |
| <b>WIP</b>     |                 | CMRP (no MSM)          |  |
| <b>WIX</b>     |                 | CMRX                   |  |

## Virtual Mount Points

| Mount Point ID  | Base Station | Communication Protocol |
|-----------------|--------------|------------------------|
| <b>VRS3</b>     | Virtual      | RTCM v3.4 (no MSM)     |
| <b>VRSP</b>     |              | CMRP (no MSM)          |
| <b>VRSX</b>     |              | CMRX (no MSM)          |
| <b>VRS3_RTX</b> |              | RTCM v3.4              |
| <b>VRSX_RTX</b> |              | CMRX                   |



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## Antenna Reference Point (ARP) Coordinates

ACORN's Default Reference Frame: **NAD 83 (2011)** – Localize your data collector for other coordinate systems or assumed values. Ensure that the latest geoid model is uploaded to the data collector for elevations in NAVD 88: **Geoid 18**

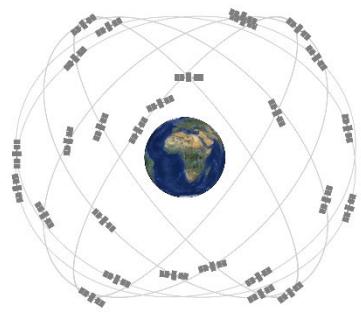
### NAD 83 (2011) Position (Epoch 2010.0)

|                   | CTBK              | CTDA              | CTEG              | CTGR              | CTGU              | CTMA              | CTNE              | CTPN              | CTWI              |
|-------------------|-------------------|-------------------|-------------------|-------------------|-------------------|-------------------|-------------------|-------------------|-------------------|
| <b>X (m)</b>      | 1,365,304.024     | 1,367,174.640     | 1,413,426.601     | 1,478,107.651     | 1,429,797.591     | 1,456,379.711     | 1,417,685.851     | 1,477,919.970     | 1,384,616.132     |
| <b>Y (m)</b>      | -4,585,218.241    | -4,617,636.827    | -4,537,671.190    | -4,562,614.120    | -4,581,509.830    | -4,539,030.813    | -4,555,729.721    | -4,518,942.746    | -4,548,662.499    |
| <b>Z (m)</b>      | 4,204,031.532     | 4,167,931.108     | 4,239,299.921     | 4,190,441.879     | 4,186,611.854     | 4,223,420.348     | 4,218,615.612     | 4,237,359.623     | 4,237,285.508     |
| <b>Lat (N)</b>    | 41° 29' 52"46411  | 41° 03' 57"06973  | 41° 55' 24"34685  | 41° 20' 07"03553  | 41° 17' 21"74218  | 41° 43' 52"91742  | 41° 40' 24"71714  | 41° 53' 59"16121  | 41° 53' 51"90726  |
| <b>Long (W)</b>   | 073° 25' 06"47519 | 073° 30' 25"94228 | 072° 41' 55"88083 | 072° 02' 58"96919 | 072° 40' 04"44444 | 072° 12' 38"87695 | 072° 42' 52"25235 | 071° 53' 22"81260 | 073° 04' 10"96819 |
| <b>Height (m)</b> | 50.410            | -13.255           | 30.276            | -18.347           | -18.105           | 55.162            | 41.759            | 53.625            | 192.096           |

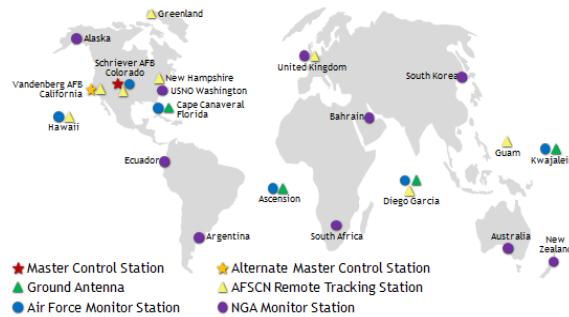
### NAD 83 (2011) Velocity (m/yr)

|                  | CTBK    | CTDA    | CTEG    | CTGR    | CTGU    | CTMA    | CTNE    | CTPN    | CTWI    |
|------------------|---------|---------|---------|---------|---------|---------|---------|---------|---------|
| <b>VX</b>        | 0.0018  | 0.0013  | 0.0018  | 0.0015  | 0.0014  | 0.0017  | 0.0012  | 0.0019  | 0.0017  |
| <b>VY</b>        | 0.0000  | 0.0014  | 0.0005  | 0.0009  | 0.0012  | 0.0007  | 0.0012  | 0.0002  | 0.0006  |
| <b>VZ</b>        | -0.0020 | -0.0024 | -0.0013 | -0.0016 | -0.0020 | -0.0016 | -0.0019 | -0.0019 | -0.0013 |
| <b>Northward</b> | -0.0018 | -0.0012 | -0.0010 | -0.0009 | -0.0010 | -0.0011 | -0.0009 | -0.0017 | -0.0009 |
| <b>Eastward</b>  | 0.0017  | 0.0016  | 0.0019  | 0.0017  | 0.0017  | 0.0018  | 0.0015  | 0.0019  | 0.0018  |
| <b>Upward</b>    | -0.0009 | -0.0023 | -0.0008 | -0.0014 | -0.0019 | -0.0012 | -0.0019 | -0.0010 | -0.0009 |

### Space Segment



### Control Segment



### User Segment



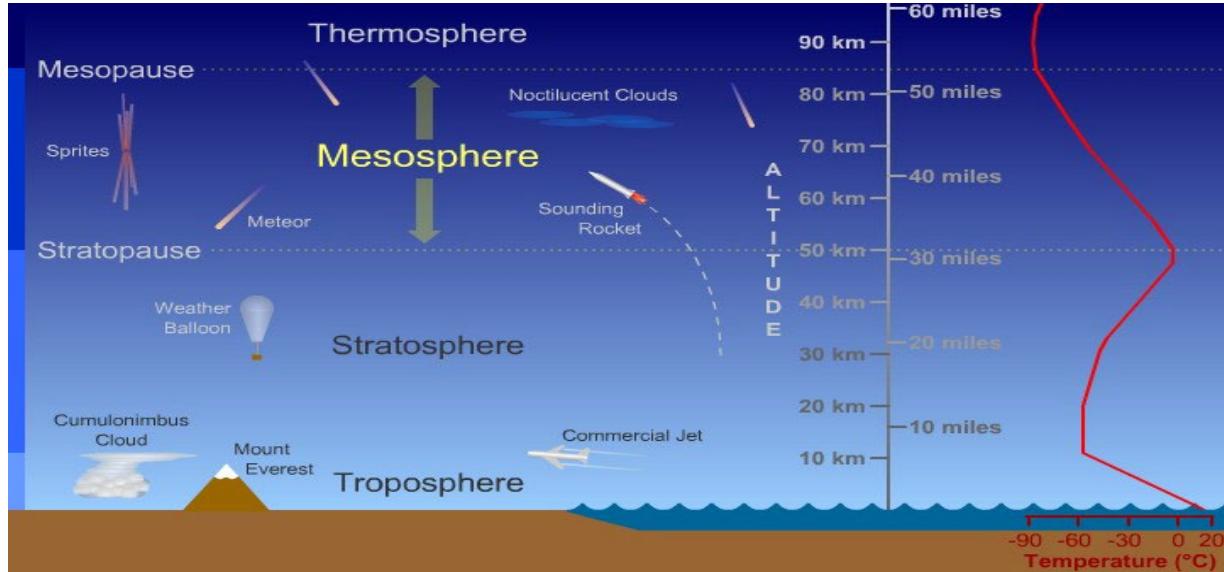


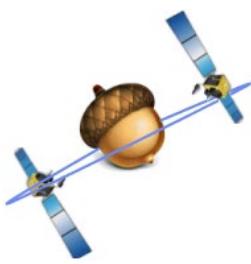
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## ALOHA (A List of Helpful Acronyms)

|         |   |       |  |
|---------|---|-------|--|
| ACORN   | Advanced Continuously Operating Reference Network     | NMEA  | National Maritime and Electronics Association      |
| CMR     | Compact Measurement Record                            | NPR   | Network Processor                                  |
| CMRP    | CMR Plus, also acronymized as CMR+                    | NTRIP | Networked Transport of RTCM via Internet Protocol  |
| CMRX    | CMR-Trimble proprietary protocol                      | ORB   | Orbit File Type                                    |
| CORS    | Continuously Operating Reference Station              | PIVOT | Progressive Infrastructure Via Overlaid Technology |
| DAT     | Data File Type  | PPE   | Post-Processing Engine                             |
| DCB     | Differential Code Bias                                | RDA   | Raw Data Analysis                                  |
| DGPS    | Differential GPS                                      | RDS   | Radio Data System                                  |
| GLONASS | Global Navigation Satellite System (in Russian)       | RINEX | Receiver Independent Exchange Format               |
| GNSS    | Global Navigation Satellite System                    | RTCM  | Radio Technical Commission for Maritime Services   |
| GPS     | Global Positioning System                             | RTK   | Real-Time Kinematic                                |
| HTML    | HyperText Markup Language                             | RTO   | Real-Time Output                                   |
| HTTP    | Hyper Text Transfer Protocol                          | SNR   | Signal-to-Noise Ratio                              |
| HTTPS   | Hyper Text Transfer Protocol Secure                   | SP3   | Standard Product #3 (by NGS)                       |
| IGS     | International Geodetic Survey                         | SQL   | Search and Query Language                          |
| IP      | Internet Protocol                                     | TEC   | Total Electron Count                               |
| IPV     | Internet Protocol Version                             | TIM   | Trimble Integrity Monitoring                       |
| IPVV    | Integrated Precipitable Water Vapor                   | URL   | Uniform Resource Locator                           |
| JPL     | Jet Propulsion Laboratory                             | VPN   | Virtual Private Network                            |
| KML     | Keyhole Markup Language                               | VRS   | Virtual Reference Station                          |
| MSM     | Multi-Signal Messages (for additional constellations) | XML   | EXtensible Markup Language                         |
| NGS     | National Geodetic Survey                              |       |  |





# ACORN FAQ



## Frequently Asked Questions

### What is ACORN?

Connecticut's Advanced Continuously Operating Reference Network is the product of a joint research project by UConn and CTDOT. The purpose was to implement a real-time network for the Connecticut Department of Transportation's Digital Design Environment.

### Is there a fee to use ACORN?

No. ACORN is currently free and open to the public.

### How do I register for a new account?

From a web browser, visit <http://acorn.uconn.edu/> and click on the Register link in the table of contents on the left side of the page. Enter your personal data, Organization, User Name, and Password. The administrator will receive notice of your registration and processes the account creation shortly afterward. If your organization already has an ACORN account, use the same organization name to keep the accounts associated.

### Does my account expire? Do my subscriptions expire?

No. Your account will remain active, and your subscriptions will be renewed annually unless you want to cancel them.

### How do I change my password?

Contact the ACORN administrator at [kevin.franklin@uconn.edu](mailto:kevin.franklin@uconn.edu) to change your password. If you change your password on your own on the web interface, the change will only take effect on the 1 server that the URL happens to route you to. ACORN runs on 2 servers for redundancy, so that will ultimately create a credentials issue.

### Can I log in with 2 devices at the same time?

No, by default, but just ask if you need to add RTK logins. Otherwise, ACORN is configured to disallow multiple simultaneous logins from the same account. To add RTK logins associated with your user account, send the ACORN administrator an email.

### Why are my elevations off by about 100 feet (30m)?

In CT, 100 feet (~30 meters) is roughly the separation between the respective surfaces of the ellipsoid and the geoid. GPS uses ellipsoid heights, so a geoid model is needed to transform to an orthometric height such as NAVD 88. If you recently purchased a new data collector or performed a hard reset, you might need to upload a geoid model that covers your project area and link it in the job settings.

### Why do my XYZ positions have a spatial offset of about 6 feet (2m)?

2 meters is roughly the difference between the origins of the NAD 83 and WGS 84 frames. You might have an option on your device to transform between NAD 83 and WGS 84. ACORN's reference frame is NAD 83.

### Does ACORN provide corrections from Galileo and Beidou?

Yes. As of July, 2025, ACORN provides signals and corrections for Galileo (EU) and Beidou (China) satellites. For users with multi-constellation capable devices, this means that several more satellites should be available at any given moment. To use the multi-constellation virtual base station, choose the mount point "VRS3\_RTX". If you have Trimble equipment, you may also choose "VRSX\_RTX", which is slightly more compact. Any mount point ending in "P" utilizes CMR+ communication protocol, which does not support multiple constellations.